Investigation of vibration parameters for needle insertion force reduction



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Introduction

- Most frequently performed routine diagnostics: blood test¹
- Requires venipuncture
- Venipuncture success depending on the skills of the clinician
- May cause severe pain or internal bleeding
- Assumption: Lower needle penetration force allows less painful insertion
- Vibration of the needle during insertion reduces penetration force²
- \rightarrow Which combination of vibration parameters enables the highest reduction?

Material and methods

- Experimental setup allows investigation of needle penetration forces during vibrating penetration
- Parameter study with different vibration frequencies and amplitudes
- 20 W loudspeaker to generate sinusoidal vibrations
- Linear motor generates linear movement for insertion procedure
- 5 N load cell with 625 Hz maximum sampling rate
- Skin simulant: 125 µm thin sheet of PET (commonly used as blood vessel replacement³), fixed with a sample holder

 \rightarrow How do the individual parameters affect the force phases during insertion?

Results

- Results can be seen in Table 1
- Insertion force was reduced by 73 % (100 Hz 500 $\mu m)$ and 67 % (200 Hz 500 $\mu m)$, respectively
- Friction force could be reduced by 74 % (10 Hz 500 μm), or by up to 100 % (100 Hz 500 μm and 200 Hz 500 μm)

Discussion

Setup:

- Speaker is not able to maintain vibration movement continuously
- Needle is currently only supported by the loudspeaker membrane
- Sampling rate of 625 Hz → Vibration frequencies are limited
 Results:
- Reduction of penetration force and frictional force by vibrating needle penetration with certain parameters was achieved

- Filtering: Moving Average Filter and 2nd order Notch Filter
- Two-sample t-tests with significance level of α = 5 %
- Investigated frequencies and amplitudes: 10, 100, 200 Hz; 20, 100, 500 μm

Experimental setup



Figure 1: Experimental setup.

Not every combination of parameters leads to a reduction

Results for puncture force and shaft friction force

Table 1: Overview of results for shaft friction force and puncture force: Force values are given in Newton and the deviations from the control insertion are given in percentage (square brackets). Values that are significantly different are marked with an asterisk.

Initial insertion force in Newton				
	0 Hz	10 Hz	100 Hz	200 Hz
0 µm	1.768 ± 0.046	_	_	_
20 µm	_	1.821 ± 0.028 [+3.04 %]	1.790 ± 0.033 [+1.26 %]	1.852* ± 0.031 [+4.76 %]
100 µm	_	1.794 ± 0.038 [+1.52 %]	1.852* ± 0.049 [+4.79 %]	1.527* ± 0.016 [-13.62 %]
500 µm	_	1.737 ± 0.035 [-1.71 %]	0.483* ± 0.014 [-72.69 %]	0.582* ± 0.047 [-67.09 %]
Shaft friction force in Newton				
0 µm	0.103 ± 0.005	_	_	_
20 µm	_	0.119* ± 0.004 [+14.72 %]	0.122* ± 0.006 [+17.91 %]	0.170* ± 0.002 [+63.83 %]
100 µm	_	0.112* ± 0.004 [+8.09 %]	0.062* ± 0.005 [-40.44 %]	0.108± 0.006 [+4.39 %]
500 µm	_	0.027* ± 0.007 [-74.00 %]	-0.018* ± 0.002 [≥ -100.0 %]	-0.026* ± 0.002 [≥ -100.00 %]

Exemplary force curve



Figure 2: Exemplary force data of a measurement with a 10 Hz – 500 μ m vibration mode. The blue line indicates the original data containing force oscillations induced by the vibration. The curves after notch filtering and after application of a moving average filter can be seen in orange and yellow, respectively. In the power spectrum in the lower graph, the increased signal amplitude at 10, 20, and 30 Hz is visible.

Conclusion

- Active position control of the vibrating loudspeaker membrane
- Investigation of more parameter combinations

Literature

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